LEVIATHAN: A STARSHIP-BASED VENUS AEROBOT FOR LOW-ALTITUDE AND SURFACE EXPLORATIONS. J. T. Vistica, Leviathan Explorations (jvistica@leviathanexplorations.com).



Introduction: Over the years numerous missions have been proposed to explore the lower altitudes and surface of Venus; however, due to the unforgiving environment, mission designs have been exceedingly limited in mass, duration, and power thus severely restricting scientific return. The Leviathan is a next-generation lander and near-surface explorer that can revolutionize our approach to exploring Venus.

The Leviathan Venus Explorer is a long-lived 30-ton nuclear-powered stainless-steel methane-filled semi-autonomous aerobot with operational altitudes from -2 km to 4 km capable of landing and taking off almost anywhere while circumnavigating Venus for possibly years.

For a rigid superpressure balloon the larger the tank size the greater the payload capacity and the potential for more scientific return. In this mission a 17 m section of Starship itself is used as the methane tank giving a lift capacity of 30 tons. This mission would be delivered by a customized SpaceX Starship on a one-way journey.

This mission is designed to take maximum advantage of reconfigured SpaceX Starship[1] components (Figure 1) allowing development costs to focus on aerobot control systems and instrument packages.

Aerobot Shell: The aerobot shell consists of a methane lift tank composed of eight standard Starship segment rings, two end caps, and a lower skirt segment (**Figure 2**). The shell mass is 15 tons leaving a payload and systems mass allowance of 15 tons.

Altitude Control System: The key to the usefulness of the aerobot is its ability to control its altitude[2]. Figure 2 shows a conceptual 3-cell vertically hung bladder almost the full height of the methane tank. Blowers use outside air to inflate the bladder to reduce lift causing the aerobot to descend. Vent valves release the air to ascend.

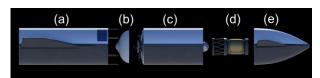


Figure 1: (a) engines and fuel tanks (50% standard size) and interstage disconnect (b) backshell with parachutes (c) Aerobot (d) cryogenic liquid helium tank (e) nose cone with interstage disconnect

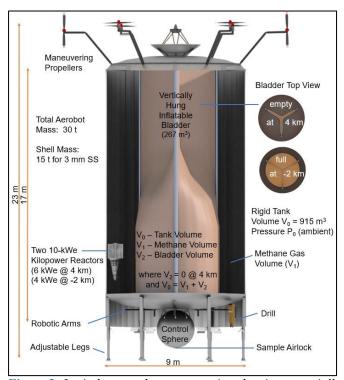


Figure 2: Leviathan aerobot cross section showing a partially filled bladder which compresses the methane space thus reducing buoyancy causing the Leviathan to descend.

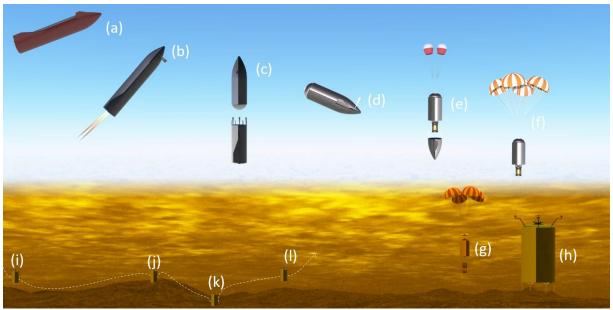


Figure 3: Venus Arrival and Mission Operations

Disassembly Maneuver: (a) atmospheric entry (b) flip to vertical (c) engines and tanks disengage (d) forward section flip (e) drogue chutes deploy and nose separation (f) main chutes deploy (g) backshell with chutes and methane tank separations at design altitude (h) system checkouts, landing legs and maneuvering arms deployed. **Surface Operations:** (i) survey surface at fixed height above ground (j) powered landing, sampling, photos, etc. (k) powered relocation to another area of interest (l) return to higher altitude to catch faster winds.

Power System: Power is provided by two self-regulating 10-kWe Kilopower[3] fission reactors located in the methane volume providing power for heat pumps, batteries, instruments, and electronics.

Lift Gas: Methane was selected as the lift gas to minimize leakage issues. 18 tons of liquid methane is transported in an external cryogenic drop tank and is gasified during initial descent to maintain positive pressure in the aerobot.

Maneuvering Propellers: High-temperature electric motors drive maneuvering propellers to assist with obstacle avoidance, landings, takeoffs, and short navigated flights.

Control Sphere: The 1.75 m diameter control sphere's internal temperature is maintained at 40 C using a bank of multi-stage coolers. About 3,200 Watts of electric power for the coolers will be needed to continually remove the projected 1,200 Watts of heat from all thermal sources.

Scientific Instruments: The Leviathan would be able to accommodate the entire list of geological and atmospheric instruments in VEXAG's Venus Flagship Mission Study[4] along with new instruments such as ground-penetrating radar, robust sample analysis in coordination with drilling activities, and an advanced

panoramic camera transmitting high-definition video as the Leviathan cruises over the Venetian landscape.

Conclusion: Previously proposed Venus landers have been limited to a single landing site and extremely limited duration. The Leviathan aerobot could possibly operate for years while circumnavigating Venus and perform surface operations anywhere along its travels. Venus conditions provide many challenges but also a unique opportunity to deliver a true global explorer in a Starship-based Leviathan aerobot.

References:

- [1] SpaceX (2021) SpaceX Starship. [Online].
- [2] Loon LLC (2021) <u>Loon Library: Lessons from</u> <u>Building Loon's Stratospheric Communications</u> <u>Service</u>
- [3] Poston D. I. et al. (2019) <u>Kilopower Reactors for</u>
 <u>Potential Space Exploration Missions</u>, NETS2019, ANS.
- [4] M. S. Gilmore, et al. (2020) <u>Venus Flagship</u> <u>Mission Decadal Study Final Report</u>, Venus Exploration Analysis Group (VEXAG).