

all three cameras contain two-dimensional CCD arrays identical to those installed in SuperCAM cameras: e2v Technologies, CCD42-10 back-illuminated high performance AIMO CCD sensors.

Sample stage and throughput capabilities. Design efforts for the SuperLIBS system focused on whole-system automation to maximize the efficiency of sample analyses at multiple plasma temperatures. A sample mount that holds up to 100 pressed powder pellets is mounted onto a two-dimensional stage with 200 mm X-Y travel and precision better than 20 μm (Griffin Motion, LM3-200-BS-A-H-S-F-00) as shown in **Figure 3**. Precise target placement under the ablation beam allows SuperLIBS to collect spectra from 100 unique locations on each 1.6 cm pellet. Therefore, ten different laser powers during a single automated run. This high sample throughput makes large-scale calibration sets feasible. We expect to collect >9 million spectra from our >3000 standards under Mars conditions over the next few years (3000 samples \times 10 locations \times 30 shots on each location \times 10 different laser powers). Use of machine learning tools for big datasets will enable creation of broadly-applicable quantitative models for prediction of chemical analyses from *Mars 2020's* SuperCAM instrument.

Instrument integration and automation. Custom Labview software was designed for SuperLIBS by R Cubed Software of Princeton, NJ. All components of SuperLIBS are synchronized to ensure that cameras record identical plasmas, and that fresh target surfaces are placed directly in the path of the focused laser beam for ablation. SuperLIBS is automated to enable long runs (up to 24 h). Prior to sample analysis, target names and relevant information are uploaded for each target, and information on integration time, number of integrations per location, number of locations per target, laser power(s), and spectrometer settings is entered (**Figure 4**). Spectra are collected and processed using LightField (Princeton Instruments), and files are exported in a format compatible with data processing employed by ChemLIBS, the LIBS instrument at

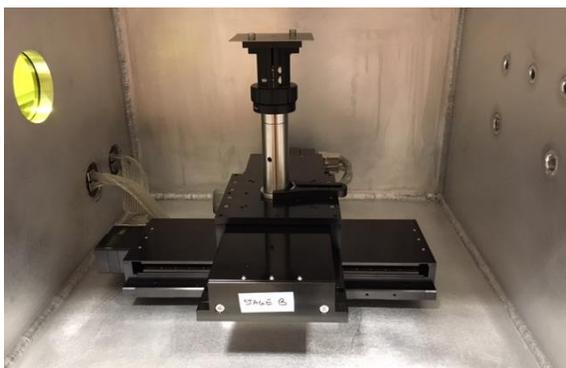


Figure 3. Sample stages inside the vacuum chamber, with Ti plate mounted at focal height on top of the stages.

Mount Holyoke College built to provide calibration support for ChemCAM (*MSL Curiosity*).

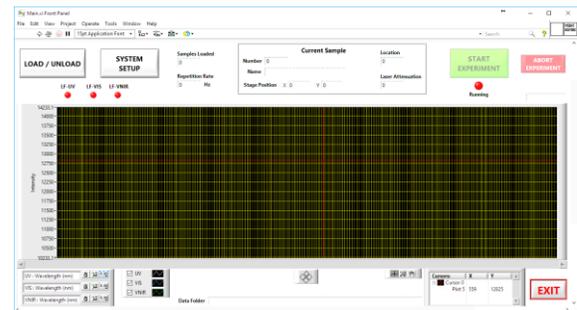


Figure 4. Main screen of custom-designed Labview software for SuperLIBS.

Data preprocessing. Protocols are analogous to those used for ChemCAM and include wavelength alignment using a Ti spectrum, subtraction of dark spectra, continuum removal, and correction for instrument response [1]. Data are normalized to detect outliers, and can be normalized for data analysis as needed.

First light/Ti spectra. SuperLIBS spectra in the VIS region collected on a Ti plate are shown with data collected on ChemLIBS for comparison (**Figure 5**), showing peak alignment between the two instruments.

The improved sensitivity and resolution of SuperLIBS' spectrometers and cameras, as well as the magnitude of data that can be rapidly collected and processed, will provide significant improvements to quan-

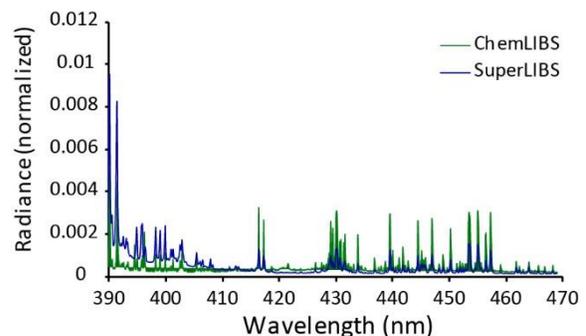


Figure 5. Ti spectra collected on SuperLIBS and ChemLIBS[8] at Mount Holyoke College, corrected for instrument response and normalized to the visible region.

tative LIBS analyses of geochemistry on Mars.

Acknowledgments: SuperLIBS was supported by a PME supplement to NASA grant NNX15AC82G.

References: [1] Wiens R.C. et al. (2013) *Spectrochim. Acta, Part B.* 82, 1–27. [2] Lanza N.L. et al. (2014) *Geophys. Res. Lett.* 41, 5755–5763. [3] Lasue J. et al. (2016) *J. Geophys. Res.* 121, 338–352. [4] Ollila M. et al. (2014) *J. Geophys. Res.* 119, 255–285. [5] Boucher T.F. et al. (2015) *Spectrochim. Acta Part B.* 107, 1–10. [6] Clegg S.M., et al. (2009) *Spectrochim. Acta Part B.*, 64, 79–88. [7] Lepore K.H. et al. (2017) *Applied Spectroscopy* 71, 1–27. [8] Dyar M. D. et al. (2016) *LPSC XLVII*, Abstract #2205.